Contemporary Linear Systems Using Matlab Bookware Companion

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Discrete Systems and Digital Signal Processing with MATLAB CRC Press
A fully updated textbook on linear systems theory Linear systems theory is the cornerstone of control theory and a well-established discipline that focuses on linear differential equations from the perspective of control and estimation. This updated second edition of Linear Systems Theory covers the subject's key topics in a unique lecture-style format, making the book easy to use for instructors and students. João Hespanha looks at system representation, stability, controllability and state feedback, observability and state estimation, and realization theory. He provides the background for advanced modern control design techniques and feedback linearization and examines advanced foundational topics, such as multivariable poles and zeros and LQG/LQR. The textbook presents only the most essential mathematical derivations and places comments, discussion, and terminology in sidebars so that readers can follow the core material easily and without distraction. Annotated proofs with sidebars explain the techniques of proof construction, including contradiction, contraposition, cycles of implications to prove equivalence, and the difference between necessity and sufficiency. Annotated theoretical developments also use sidebars to discuss relevant commands available in MATLAB, allowing students to understand these tools. This second edition contains a large number of new practice exercises with solutions. Based on typical problems, these exercises guide students to succinct and precise answers, helping to clarify issues and consolidate knowledge. The book's balanced chapters can each be covered in approximately two hours of lecture time, simplifying course planning and student review. Easy-to-use textbook in unique lecture-style format Sidebars explain topics in further detail Annotated proofs and discussions of MATLAB commands Balanced chapters can each be taught in two hours of course lecture New practice exercises with solutions included
Electronics and Circuit Analysis Using MATLAB Vikas Publishing House
Learn MATLAB while mastering linear algebra The MATLAB Technology Resource Manual to accompany Contemporary Linear Algebra helps students get comfortable with the technology so they can focus on learning math. The text takes a unique approach to linear algebra, fostering mathematical thinking and problem-solving skills over rote memorization; this supplement helps you use technology to achieve mathematical precision and streamline your work flow to mirror real-world applications. MATLAB is ubiquitous in the STEM fields, and gaining a robust set of fundamental skills now, while learning algebra, will pay off heavily in the coming years.
Modeling and Simulation of Systems Using MATLAB and Simulink Brooks/Cole
Modern control theory and in particular state space or state variable methods can be adapted to the description of many different systems because it depends strongly on physical modeling and physical intuition. The laws of physics are in the form of differential equations and for this reason, this book concentrates on system descriptions in this form. This means coupled systems of linear or nonlinear differential equations. The physical

approach is emphasized in this book because it is most natural for complex systems. It also makes what would ordinarily be a difficult mathematical subject into one which can straightforwardly be understood intuitively and which deals with concepts which engineering and science students are already familiar. In this way it is easy to immediately apply the theory to the understanding and control of ordinary systems. Application engineers, working in industry, will also find this book interesting and useful for this reason. In line with the approach set forth above, the book first deals with the modeling of systems in state space form. Both transfer function and differential equation modeling methods are treated with many examples. Linearization is treated and explained first for very simple nonlinear systems and then more complex systems. Because computer control is so fundamental to modern applications, discrete time modeling of systems as difference equations is introduced immediately after the more intuitive differential equation models. The conversion of differential equation models to difference equations is also discussed at length, including transfer function formulations. A vital problem in modern control is how to treat noise in control systems. Nevertheless this question is rarely treated in many control system textbooks because it is considered to be too mathematical and too difficult in a second course on controls. In this textbook a simple physical approach is made to the description of noise and stochastic disturbances which is easy to understand and apply to common systems. This requires only a few fundamental statistical concepts which are given in a simple introduction which lead naturally to the fundamental noise propagation equation for dynamic systems, the Lyapunov equation. This equation is given and exemplified both in its continuous and discrete time versions. With the Lyapunov equation available to describe state noise propagation, it is a very small step to add the effect of measurements and measurement noise. This gives immediately the Riccati equation for optimal state estimators or Kalman filters. These important observers are derived and illustrated using simulations in terms which make them easy to understand and easy to apply to real systems. The use of LQR regulators with Kalman filters give LQG (Linear Quadratic Gaussian) regulators which are introduced at the end of the book. Another important subject which is introduced is the use of Kalman filters as parameter estimations for unknown parameters. The textbook is divided into 7 chapters, 5 appendices, a table of contents, a table of examples, extensive index and extensive list of references. Each chapter is provided with a summary of the main points covered and a set of problems relevant to the material in that chapter. Moreover each of the more advanced chapters (3 - 7) are provided with notes describing the history of the mathematical and technical problems which lead to the control theory presented in that chapter. Continuous time methods are the main focus in the book because these provide the most direct connection to physics. This physical foundation allows a logical presentation and gives a good intuitive feel for control system construction. Nevertheless strong attention is also given to discrete time systems. Very few proofs are included in the book but most of the important results are derived. This method of presentation makes the text very readable and gives a good foundation for reading more rigorous texts. A complete set of solutions is available for all of the problems in the text. In addition a set of longer exercises is available for use as Matlab/Simulink 'laboratory exercises' in connection with lectures. There is material of this kind for 12 such exercises and each exercise requires about 3 hours for its solution. Full written solutions of all these exercises are available.

Modern Linear Control Design Springer Science & Business Media

In this book, Tewari emphasizes the physical principles and engineering applications of modern control system design. Instead of detailing the mathematical theory, MATLAB examples are used throughout.

Modern Control Systems Analysis and Design Using MATLAB CRC Press

Control Systems Engineering using MATLAB provides students with a concise introduction to the basic concepts in automatic control systems and the various methods of solving its problems. Designed to comfortably cover two academic semesters, the style and form of the book makes it easily comprehensible for all engineering disciplines that have control system courses in their curricula. The solutions to the problems are programmed using MATLAB 6.0 for which the simulated results are provided. The MATLAB Control Systems Toolbox is provided in the Appendix for easy reference. The book would be useful as a textbook to undergraduate students and as quick reference for higher studies.

Practical MATLAB Applications for Engineers Wiley

This supplement to any standard communication systems text is one of the first books to successfully integrate the use of MATLAB in the study of communication systems concepts and problems. It has been developed for instructors and students who wish to make use of MATLAB as an integral part of their study. The former will find the means by which to use MATLAB as a powerful tool to motivate students and illustrate essential theory without having to customize the applications themselves; the latter will find relevant problems quickly and easily. The book includes numerous MATLAB-based simulations and examples of communication systems, while providing a good balance of theory and hands-on computer experience. This Updated Printing revises the book and MATLAB files (available for downloading from the Brooks/Cole Bookware Companion Resource Center Web Site) to MATLAB V5.

Fundamentals of Linear Control CRC Press

Learn to use MATLAB® as a useful computing tool for exploring traditional Digital Signal Processing (DSP) topics and solving problems to gain insight with this supplementary text. DIGITAL SIGNAL PROCESSING USING MATLAB®: A PROBLEM SOLVING COMPANION, 4E greatly expands the range and complexity of problems that you can effectively study. Since DSP applications are primarily algorithms implemented on a DSP processor or software, they require a significant amount of programming. Using interactive software, such as MATLAB®, enables you to focus on mastering new and challenging concepts rather than concentrating on programming algorithms. This edition discusses interesting, practical examples and explores useful problems. New online chapters introduce advanced topics, such as optimal filters, linear prediction, and adaptive filters, which are essential in furthering your academic studies at the graduate level.

Principles of System Identification Princeton University Press

This is a title in the PWS series BookWare Companion Series. It is a set of correlated, self-contained courseware modules covering fundamental concepts in engineering and applied mathematics. Students work through example problems electronically, and are encouraged to experiment with problems and data in an electronic lab setting. Each BookWare Companion features a software script for the electronic examples, based on a popular applications software package for the IBM PC or the Macintosh, and a printed volume containing computer-based exploration exercises and a variety of learning aids and hints. The text - bolstered by illustrative examples, 200 problems and MATLAB exploration exercises on the accompanying data disk - should enable students to work with linear systems problems in a virtual laboratory at the computer, changing problem values at will in a what-if fashion.

Modern Control Design Cengage Learning

Introduction to Linear Control Systems is designed as a standard introduction to linear control systems for all those who one way or another deal with control systems. It can be used as a comprehensive up-to-date textbook for a one-semester 3-credit undergraduate course on linear control systems as the first course on this topic at university. This includes the faculties of electrical engineering, mechanical engineering, aerospace engineering, chemical and petroleum engineering, industrial engineering, civil engineering, bio-engineering, economics, mathematics, physics, management and social sciences, etc. The book covers foundations of linear control systems, their raison detre, different types, modelling, representations, computations, stability concepts, tools for time-domain and frequency-domain analysis and synthesis, and fundamental limitations, with an emphasis on frequency-domain methods. Every chapter includes a part on further readings where more advanced topics and pertinent references are introduced for further studies. The presentation is theoretically firm, contemporary, and self-contained. Appendices cover Laplace transform and differential equations, dynamics, MATLAB and SIMULINK, treatise on stability concepts and tools, treatise on Routh-Hurwitz method, random optimization techniques as well as convex and non-convex problems, and sample midterm and endterm exams. The book is divided to the sequel 3 parts plus appendices. PART I: In this part of the book, chapters 1-5, we present foundations of linear control systems. This includes: the introduction to control systems, their raison detre, their different types, modelling of control systems, different methods for their representation and fundamental computations, basic stability concepts and tools for both analysis and design, basic time domain analysis and design details, and the root locus as a stability analysis and synthesis tool. PART II: In this part of the book, Chapters 6-9, we present what is generally referred to as the frequency domain methods. This refers to the experiment of applying a sinusoidal input to the system and studying its output. There are basically three different methods for representation and studying of the data of the aforementioned frequency response experiment: these are the Nyquist plot, the Bode diagram, and the Krohn-Manger-Nichols chart. We study these methods in details. We learn that the output is also a sinusoid with the same frequency but generally with different phase and magnitude. By dividing the output by the input we obtain the so-called sinusoidal or frequency transfer function of the system which is the same as the transfer function when the Laplace variable s is substituted with . Finally we use the Bode diagram for the design process. PART III: In this part, Chapter 10, we introduce some miscellaneous advanced topics under the theme fundamental limitations which should be included in this undergraduate course at least in an introductory level. We make bridges between some seemingly disparate aspects of a control system and theoretically complement the previously studied subjects. Appendices: The book contains seven appendices. Appendix A is on the Laplace transform and differential equations. Appendix B is an introduction to dynamics. Appendix C is an introduction to MATLAB, including SIMULINK. Appendix D is a survey on stability concepts and tools. A glossary and road map of the available stability concepts and tests is provided which is missing even in the research literature. Appendix E is a survey on the Routh-Hurwitz method, also missing in the literature. Appendix F is an introduction to random optimization techniques and convex and non-convex problems. Finally, appendix G presents sample midterm and endterm exams, which are class-tested several times.

Linear Systems Control CL Engineering

Continuous Signals and Systems with MATLAB® offers broad, detailed, and focused comprehensive coverage of continuous linear systems, based on basic mathematical principles. It presents many solved problems from various engineering disciplines using analytical tools as well as MATLAB. This book is intended primarily for undergraduate junior and senior electrical, mechanical, aeronautical, and aerospace engineering students. Practicing engineers will also find this book useful. This book is ideal for use in a one-semester course in continuous linear systems where the instructor can easily cover all of the chapters. Each chapter presents numerous examples that illustrate each concept. Most of the worked-out examples are first solved analytically, and then solved using MATLAB in a clear and understandable fashion. This book concentrates on explaining the subject matter with easy-to-follow mathematical development and numerous solved examples. The book covers traditional topics and includes an extensive coverage of state-space representation and analysis. The reader does not need to be fluent in MATLAB because the examples are presented in a self-explanatory way.

Linear Control System Analysis and Design with MATLAB®, Sixth Edition Jones & Bartlett Publishers

Featuring a variety of applications that motivate students, this book serves as a companion or supplement to any of the comprehensive textbooks in communication systems. The book provides a variety of exercises that may be solved on the computer using MATLAB. By design, the treatment of the various topics is brief. The authors provide the motivation and a short introduction to each topic, establish the necessary notation, and then illustrate the basic concepts by means of an example. Important Notice: Media content referenced within the product description or the product text may not be available in the ebook version.

Numerical Methods Using Matlab CRC Press

Ideal for those in science and industry, this state-of-the-art guide to using MATLAB introduces readers to a wide range of numerical algorithms implemented by this modern and powerful computer software—with full explanations of their fundamental principles and clear visual interpretation of results using MATLAB graphics.Provides clear visual interpretation of results using MATLAB graphics, and discusses the solution of linear equations and eigenvalue problems; methods for solving non-linear equations; numerical integration and differentiation; the solution of initial value and boundary value problems; curve fitting including splines, leas squares, and Fourier analysis. Integrates developing computer technology through all algorithms and scripts, encourages systematic experimentation, and offers a thorough, hands-on study of MATLAB functions that includes optimization and regression analysis with applications of symbolic methods.For electrical engineers.

Introduction to Linear Control Systems CRC Press

This new edition provides an updated approach for students, engineers, and researchers to apply numerical methods for solving problems using MATLAB® This accessible book makes use of MATLAB® software to teach the fundamental concepts for applying numerical methods to solve practical engineering and/or science problems. It presents programs in a complete form so that readers can run them instantly with no programming

skill, allowing them to focus on understanding the mathematical manipulation process and making interpretations of the results. Applied Numerical Methods Using MATLAB®, Second Edition begins with an introduction to MATLAB usage and computational errors, covering everything from input/output of data, to various kinds of computing errors, and on to parameter sharing and passing, and more. The system of linear equations is covered next, followed by a chapter on the interpolation by Lagrange polynomial. The next sections look at interpolation and curve fitting, nonlinear equations, numerical differentiation/integration, ordinary differential equations, and optimization. Numerous methods such as the Simpson, Euler, Heun, Runge-kutta, Golden Search, Nelder-Mead, and more are all covered in those chapters. The eighth chapter provides readers with matrices and Eigenvalues and Eigenvectors. The book finishes with a complete overview of differential equations. Provides examples and problems of solving electronic circuits and neural networks Includes new sections on adaptive filters, recursive least-squares estimation, Bairstow's method for a polynomial equation, and more Explains Mixed Integer Linear Programing (MILP) and DOA (Direction of Arrival) estimation with eigenvectors Aimed at students who do not like and/or do not have time to derive and prove mathematical results Applied Numerical Methods Using MATLAB®, Second Edition is an excellent text for students who wish to develop their problem-solving capability without being involved in details about the MATLAB codes. It will also be useful to those who want to delve deeper into understanding underlying algorithms and equations.

Linear Feedback Control John Wiley & Sons

The sparse backslash book. Everything you wanted to know but never dared to ask about modern direct linear solvers. Chen Greif, Assistant Professor, Department of Computer Science, University of British Columbia.Overall, the book is magnificent. It fills a long-felt need for an accessible textbook on modern sparse direct methods. Its choice of scope is excellent John Gilbert, Professor, Department of Computer Science, University of California, Santa Barbara.Computational scientists often encounter problems requiring the solution of sparse systems of linear equations. Attacking these problems efficiently requires an in-depth knowledge of the underlying theory, algorithms, and data structures found in sparse matrix software libraries. Here, Davis presents the fundamentals of sparse matrix algorithms to provide the requisite background. The book includes CSparse, a concise downloadable sparse matrix package that illustrates the algorithms and theorems presented in the book and equips readers with the tools necessary to understand larger and more complex software packages.With a strong emphasis on MATLAB and the C programming language, Direct Methods for Sparse Linear Systems equips readers with the working knowledge required to use sparse solver packages and write code to interface applications to those packages. The book also explains how MATLAB performs its sparse matrix computations.Audience This invaluable book is essential to computational scientists and software developers who want to understand the theory and algorithms behind modern techniques used to solve large sparse linear systems. The book also serves as an excellent practical resource for students with an interest in combinatorial scientific computing.Preface; Chapter 1: Introduction; Chapter 2: Basic algorithms; Chapter 3: Solving triangular systems; Chapter 4: Cholesky factorization; Chapter 5: Orthogonal methods; Chapter 6: LU factorization; Chapter 7: Fill-reducing orderings; Chapter 8: Solving sparse linear systems; Chapter 9: CSparse; Chapter 10: Sparse matrices in MATLAB; Appendix: Basics of the C programming language; Bibliography; Index.

Contemporary Linear Systems Using MATLAB 4.0 CRC Press

Numerical Methods with MATLAB provides a highly-practical reference work to assist anyone working with numerical methods. A wide range of techniques are introduced, their merits discussed and fully working MATLAB code samples supplied to demonstrate how they can be coded and applied. Numerical methods have wide applicability across many scientific, mathematical, and engineering disciplines and are most often employed in situations where working out an exact answer to the problem by another method is impractical. Numerical Methods with MATLAB presents each topic in a concise and readable format to help you learn fast and effectively. It is not intended to be a reference work to the conceptual theory that underpins the numerical methods themselves. A wide range of reference works are readily available to supply this information. If, however, you want assistance in applying numerical methods then this is the book for you.

MATLAB Technology Resource Manual by Herman Gollwitzer to accompany Contemporary Linear Algebra Wiley

Not only do modeling and simulation help provide a better understanding of how real-world systems function, they also enable us to predict system behavior before a system is actually built and analyze systems accurately under varying operating conditions. Modeling and Simulation of Systems Using MATLAB® and Simulink® provides comprehensive, state-of-the-art coverage of all the important aspects of modeling and simulating both physical and conceptual systems. Various real-life examples show how simulation plays a key role in understanding real-world systems. The author also explains how to effectively use MATLAB and Simulink software to successfully apply the modeling and simulation techniques presented. After introducing the underlying philosophy of systems, the book offers step-by-step procedures for modeling different types of systems using modeling techniques, such as the graph-theoretic approach, interpretive structural modeling, and system dynamics modeling. It then explores how simulation evolved from pre-computer days into the current science of today. The text also presents modern soft computing techniques, including artificial neural networks, fuzzy systems, and genetic algorithms, for modeling and simulating complex and nonlinear systems. The final chapter addresses discrete systems modeling. Preparing both undergraduate and graduate students for advanced modeling and simulation courses, this text helps them carry out effective simulation studies. In addition, graduate students should be able to comprehend and conduct simulation research after completing this book.

Digital Signal Processing Using MATLAB & Wavelets CRC Press

Optimal Networked Control Systems with MATLAB® discusses optimal controller design in discrete time for networked control systems (NCS). The authors apply several powerful modern control techniques in discrete time to the design of intelligent controllers for such NCS. Detailed derivations, rigorous stability proofs, computer simulation examples, and downloadable MATLAB® codes are included for each case. The book begins by providing background on NCS, networked imperfections, dynamical systems, stability theory, and stochastic optimal adaptive controllers in discrete time for linear and nonlinear systems. It lays the foundation for reinforcement learning-based optimal adaptive controller use for finite and infinite horizons. The text then: Introduces quantization effects for linear and nonlinear NCS, describing the design of stochastic adaptive controllers for a class of linear and nonlinear systems Presents two-player zero-sum game-theoretic formulation for linear systems in input–output form enclosed by a communication network Addresses the stochastic optimal control of nonlinear NCS by using neuro dynamic programming Explores stochastic optimal design for nonlinear two-player zero-sum games under communication constraints Treats an event-sampled distributed NCS to minimize transmission of state and control signals within the feedback loop via the communication network Covers distributed joint optimal network scheduling and control design for wireless NCS, as well as the effect of network protocols on the wireless NCS controller design An ideal reference for graduate students, university researchers, and practicing engineers, Optimal Networked Control Systems with MATLAB® instills a solid understanding of neural network controllers and how to build them.

Linear Control System Analysis and Design Cambridge University Press

This book is a supplement for any standard control systems text. It serves to reinforce the learning process for those who are studying introductory aspects of control systems. The authors accomplish this by teaching the use of MATLAB® and its CONTROL SYSTEM TOOLBOX to rapidly solve a wide range of numerical problems. This book also provides the user with opportunities to apply techniques of linear system analysis, which forms the basis for the analysis and design of feedback control systems. This approach frees the user from the laborious calculations required to solve meaningful problems, thus allowing him or her to concentrate on interpreting the analysis and design results. Topical coverage includes both classical control design method and state-space models and design methods. Some specific topics covered are root-locus plots, frequency-response analysis, system performance, proportional-integral-derivative control, and frequency-response design. This updated printing revises the book and code examples (available for downloading from the Brooks/Cole Web site) to MATLAB® V5.

Numerical Linear Algebra with Applications Apress

Designed for a one-semester undergraduate course in continuous linear systems, Continuous Signals and Systems with MATLAB®, Second Edition presents the tools required to design, analyze, and simulate dynamic systems. It thoroughly describes the process of the linearization of nonlinear systems, using MATLAB® to solve most examples and problems. With updates and revisions throughout, this edition focuses more on state-space methods, block diagrams, and complete analog filter design. New to the Second Edition • A chapter on block diagrams that covers various classical and state-space configurations • A completely revised chapter that uses MATLAB to illustrate how to design, simulate, and implement analog filters • Numerous new examples from a variety of engineering disciplines, with an emphasis on electrical and electromechanical engineering problems Explaining the subject matter through easy-to-follow mathematical development as well as abundant examples and problems, the text covers signals, types of systems, convolution, differential equations,Fourier series and transform, the Laplace transform, state-space representations, block diagrams, system linearization, and analog filter design. Requiring no prior fluency with MATLAB, it enables students to master both the concepts of continuous linear systems and the use of MATLAB to solve problems.

Digital Signal Processing Using MATLAB Createspace Independent Publishing Platform

Master Techniques and Successfully Build Models Using a Single Resource Vital to all data-driven or measurement-based process operations, system identification is an interface that is based on observational science, and centers on developing mathematical models from observed data. Principles of System Identification: Theory and Practice is an introductory-level book that presents the basic foundations and underlying methods relevant to system identification. The overall scope of the book focuses on system identification with an emphasis on practice, and concentrates most specifically on discrete-time linear system identification. Useful for Both Theory and Practice The book presents the foundational pillars of identification, namely, the theory of discrete-time LTI systems, the basics of signal processing, the theory of random processes, and estimation theory. It explains the core theoretical concepts of building (linear) dynamic models from experimental data, as well as the experimental and practical aspects of identification. The author offers glimpses of modern developments in this area, and provides numerical and simulation-based examples, case studies, end-of-chapter problems, and other ample references to code for illustration and training. Comprising 26 chapters, and ideal for coursework and self-study, this extensive text: Provides the essential concepts of identification Lays down the foundations of mathematical descriptions of systems, random processes, and estimation in the context of identification Discusses the theory pertaining to non-parametric and parametric models for deterministic-plus-stochastic LTI systems in detail Demonstrates the concepts and methods of identification on different case-studies Presents a gradual development of state-space identification and grey-box modeling Offers an overview of advanced topics of identification namely the linear time-varying (LTV), non-linear, and closed-loop identification Discusses a multivariable approach to identification using the iterative principal component analysis Embeds MATLAB® codes for illustrated examples in the text at the respective points Principles of System Identification: Theory and Practice presents a formal base in LTI deterministic and stochastic systems modeling and estimation theory; it is a one-stop reference for introductory to moderately advanced courses on system identification, as well as introductory courses on stochastic signal processing or time-series analysis.The MATLAB scripts and SIMULINK models used as examples and case studies in the book are also available on the author's website: http://arunkt.wix.com/homepage#!textbook/c397